

# Frame type theory

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# Goal

We want a nice dependently-typed calculus that allows for modular definitions and proofs and minimizes boilerplate

# Alternance of axioms and definitions: the advent of boilerplate

It's **not** about expressivity

**Axiom** car : Type

**Definition** binary\_op := car → car → car

**Axiom** mult : binary\_op *(\* written . \*)*

**Definition** mult\_associative :  $\prod (x,y,z : \text{car}),$   
 $(x \cdot y) \cdot z = x \cdot (y \cdot z)$

**Axiom** op\_associator : op\_associative

# Alternance of axioms and definitions: the advent of boilerplate

It's **not** about expressivity

```
Axiom car : Type
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```
Definition binary_op := car → car → car
```

```
Axiom mult : binary_op (* written *)
```

```
Definition mult_associative : Π (x,y,z : car),  
  (x · y) · z = x · (y · z)
```

```
Axiom op_associator : op_associative
```

---

```
Definition binary_op (car : Type) := car → car → car
```

```
Definition mult_associative (cat : Type)  
  (mult : binary_op car) : Π (x,y,z : car),  
  (x · y) · z = x · (y · z)
```

```
Axiom car : Type
```

```
Axiom mult : binary_op car (* written *)
```

```
Axiom op_associator : op_associative car mult
```

# Alternance of axioms and definitions: the advent of boilerplate

Too much boilerplate!

```
Definition def1 := ...
```

```
Definition def2 (proof1 : axiom1 def1) := ...
```

```
Definition def3 (proof1 : axiom1 def1)  
                (proof2 : axiom2 def1 (def2 proof1)) := ...
```

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## Problem

If  $n$  alternations,  $\Theta(n^3)$  boilerplate code!

# First-class objects, subsuming records

Definition by induction

```
1 Definition trivial_monoid : Mon :=  
2   { car := unit, e := (), ... }  
3 Definition monoid_product (M1 M2 : Mon) : Mon :=  
4   { car := M1.car × M2.car, e := (M1.e, M2.e), ... }
```

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```
5 Definition monoid_power (M : Mon) (n : nat) : Mon := {
6   car := iter unit (λx. x × M.car) n,
7   e := iter () (λx. (x, M.car)),
8   ...
9 }
```



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```

---

```
10 Definition monoid_power (M : Mon) (n : nat) : Mon :=
11   iter unit_monoid (λx. monoid_product x M)

```

# First-class objects, subsuming records

## Quantification

```
1 Lemma quantifier_elimination :  
2    $\Pi$  (F : ReadClosedField),  
3    $\Pi$  ( $\varphi$  : Formula),  
4    $\Sigma$  ( $\psi$  : ClosedFormula),  
5    $\llbracket \varphi \rrbracket_F = \llbracket \psi \rrbracket_F$ 
```

## Named abstraction and application

- ▶ No  $\alpha$ -renaming: Abstraction replaced by empty fields:  
 $\lambda x_1.(x_2 := t, \lambda x_3.(x_4 := t', x_5 := t''))$  becomes  
 $x_1 := ?, x_2 := t, x_3 := ?, x_4 := t', x_5 := t''$

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- ▶ Reduction:

$\{(x_1 := ?, x_2 := ?, x_3 := x_1 + x_2, x_4 := ?, x_5 := x_3 + x_4) (x_1 := 2, x_2 := 3)\} .x_3$

$\nabla_*$

$\{x_1 := 2, x_2 := 3, x_3 := x_1 + x_2, x_4 := ?, x_5 := x_3 + x_4\} .x_3$

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$\{x_1 := 2, x_2 := 3, x_3 := 2 + 3, x_4 := ?, x_5 := x_3 + x_4\} .x_3$

$\nabla_*$

$2 + 3$

# Definitional singleton, subsuming modules

- ▶ Type may need to know the value of a field:

$$\{x^{\text{Type}} := \mathbb{N}, y^x := 0, z^{y=0} := \text{refl}\} : \Sigma x^{\text{Type}}, \Sigma y^x, \Sigma z^{y=0}$$

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- ▶ Remember the value in the type;

$$\{x^{\text{Type}} \stackrel{\Delta}{=} \mathbb{N}, y^x \stackrel{\Sigma}{=} 0, z^{y=0} \stackrel{\Sigma}{=} \text{refl}\} : \Delta x^{\text{Type}} := \mathbb{N}, \Sigma y^x, \Sigma z^{y=0}$$

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- ▶ Typing rules

$$\frac{\Gamma \vdash \varphi : \Sigma x^A, \mathcal{B}}{\Gamma \vdash \varphi.x : A}$$

$$\frac{\Gamma \vdash \varphi : \Delta x^A := t, \mathcal{B}}{\Gamma \vdash \varphi.x : A}$$

$$\frac{\Gamma \vdash \varphi : \Delta x^A := t, \mathcal{B}}{\Gamma \vdash \varphi.x \equiv t : A}$$



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- ▶ Simulates let expressions:

$$\text{let } x := t \text{ in } u \approx \{x \doteq t, y := u\}.y$$

# Field commutations, maybe subsuming sections

If  $x \notin \text{FV}(u) \cap \text{FV}(B)$  and  $y \notin \text{FV}(t) \cap \text{FV}(A)$ , then:

$$\begin{aligned}\Sigma x^A, \Sigma y^B, \mathcal{C} &\equiv \Sigma y^B, \Sigma x^A, \mathcal{C} \\ \Delta x^A := t, \Delta y^B := u, \mathcal{C} &\equiv \Delta y^B := u, \Delta x^A := t, \mathcal{C} \\ \Delta x^A := t, \Sigma y^B, \mathcal{C} &\equiv \Sigma y^B, \Delta x^A := t, \mathcal{C}\end{aligned}$$

$$x^A := t, y^B := u, \varphi \equiv y^B := u, x^A := t, \varphi$$

$$\Pi x^A, \Pi y^B, \mathcal{C} \equiv \Pi y^B, \Pi x^A, \mathcal{C}$$

$$x^A := ?, y^B := ?, \varphi \equiv y^B := ?, x^A := ?, \varphi$$

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$$x^A := t, y^B := u, \varphi \equiv y^B := u, x^A := t, \varphi$$

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Need more commutations to simulate minimal discharge of sections

# Modularity

- ▶ Renaming operator: necessary to combine libraries with different naming conventions
- ▶ Includes:

$$\text{PtTopSpace} := \{ \text{car}^{\text{Type}} :=?, \text{pt}^{\text{car}} :=?, \text{top}^{\mathcal{P}(\mathcal{P}(\text{car}))} :=?, \dots \}$$
$$\text{Group} := \{ \text{car}^{\text{Type}} :=?, \text{e}^{\text{car}} :=?, \text{mult}^{\text{car} \rightarrow \text{car} \rightarrow \text{car}} :=?, \dots \}$$
$$\begin{aligned} \text{TopGroup} := \{ & \\ & \text{include}(\text{Group}), \\ & \text{smart\_include}(\text{rename}_{\text{pt} \rightarrow \text{e}}(\text{Group})), \\ & \text{mult\_cont} := \dots, \\ & \dots \\ & \} \end{aligned}$$

# Conclusion

- ▶ Work in progress: candidate calculus
- ▶ Expected properties:
  - ▶ Conservative over MLTT (with definitional singleton)
  - ▶ Subsumes modules (minus subtyping) and records (and hopefully section)
  - ▶ No code duplication, and minimal boilerplate